



## Automated Methodology for extracting Citywide Prominent Ridgelines using DEM & challenges faced in using LAR-IAC 2' DEM in similar process

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## Objective

- Provide a citywide prominent ridgeline base map for planners
  - To design their policy guidelines for future developments
  - Limit expansion of urban development into ridgeline protection areas
  - Minimize the visual impacts of hillside development & preserve scenic ridgelines.
  - Reasonable care on unstable hillsides

## Overview

Input : DEM (USGS 10 m)

Output: Flow Direction  
Flow Accumulation  
Watershed  
Curvature  
Topological Positioning Index  
Slope

Possible Ridgelines

Prominent Ridgelines

## Ridgelines

A narrow range of mountains.

**Primary Ridgelines** : A Ridgeline which is prominently visible from a substantial land area, or from a major transportation corridor.

**Secondary Ridgelines**: Typically lower, compared with surrounding terrain, and may be visible only to a limited area.



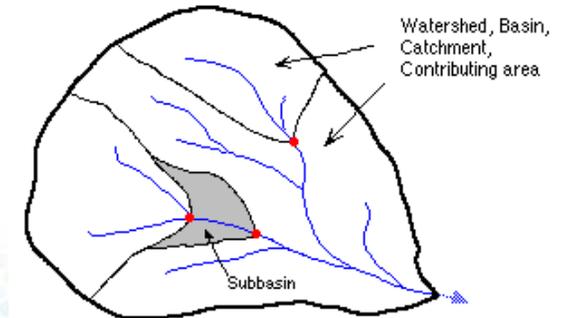
# Methodology

1. Derive derivatives of DEM :  
Watershed, Slope, Curvature,  
Topological positioning Index  
(TPI)
2. Use DEM Derivatives in Binary  
Decision Tree Algorithm

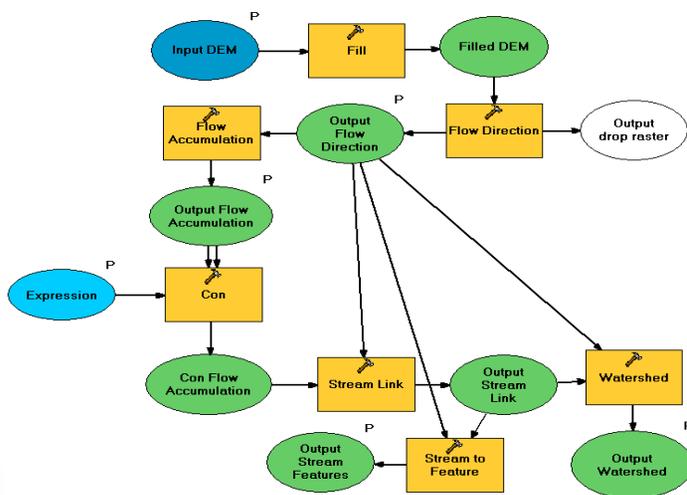


# Watershed

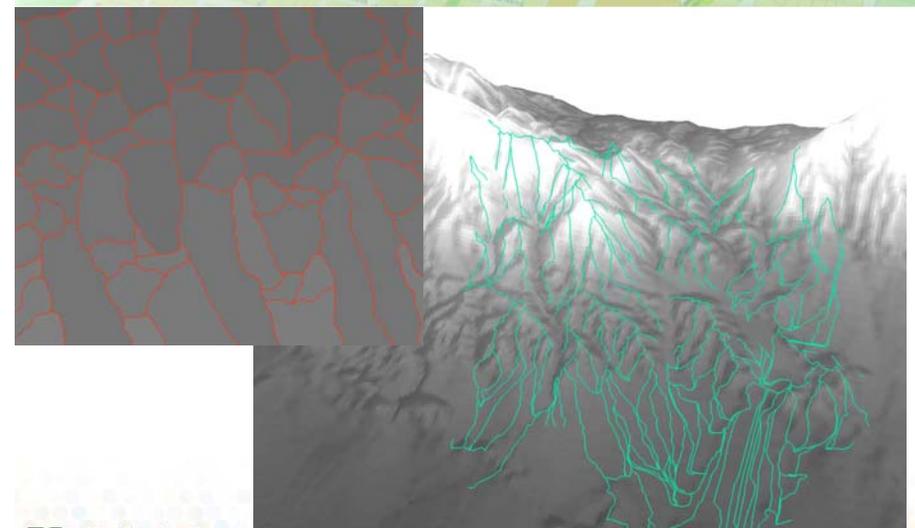
- “Watershed” is a catchment basin that conveys all surface and ground water that falls within it & runs through it.
- It is geographically delineated by highest ridgelines.



# Watershed Delineation



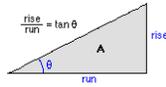
# Watershed boundaries Possible Ridgelines



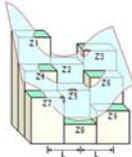
# DEM Derivatives

## Slope

Degree of slope =  $\theta$   
 Percent of slope =  $\frac{\text{rise}}{\text{run}} \times 100$



## Curvature



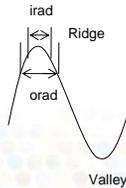
$$Z = Ax^2y^2 + Bx^2y + Cxy^2 + Dx^2 + Ey^2 + Fxy + Gx + Hy + I$$

## Topological Positioning Index (Andrew Weiss, 2001)

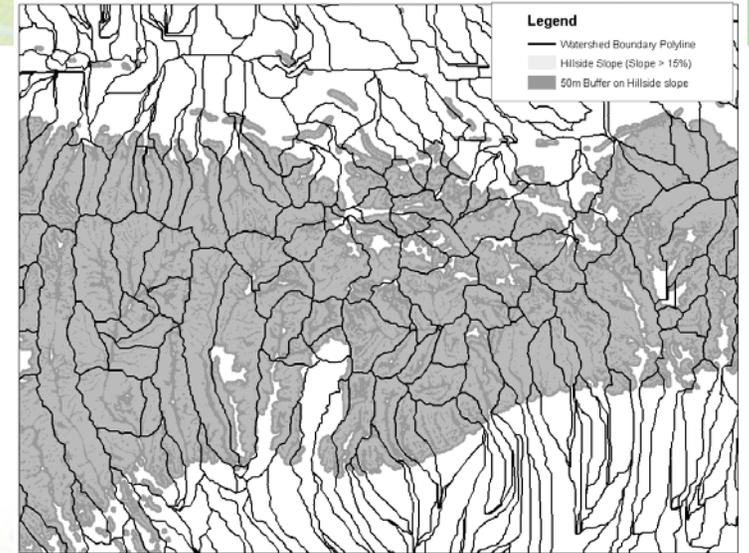
$$tpi = (elevation - focal\_mean(elevation, annulus, irad, orad)) + 0.5$$

TPI<sub>500</sub>; irad= 45m, orad=50m

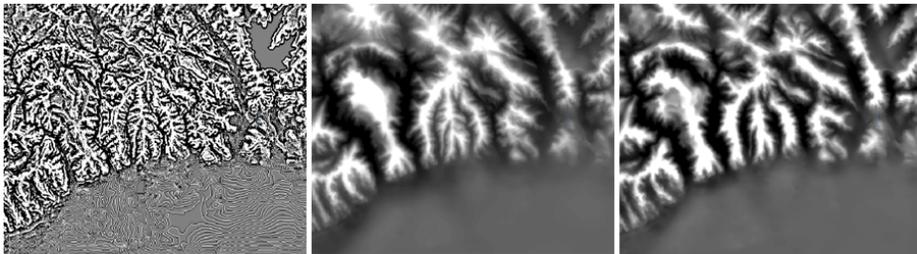
TPI<sub>300</sub>; irad=25m, orad=30m



# Slope



# DEM Derivatives



(a)

Curvature

(b)

ST<sub>1</sub>

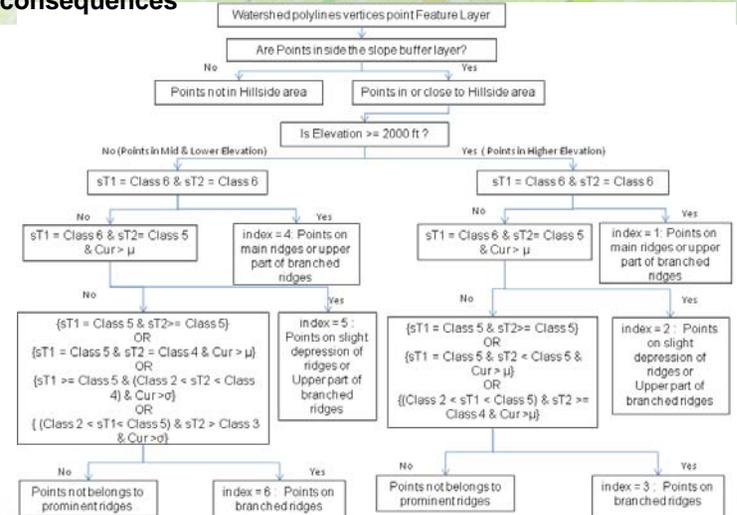
(c)

ST<sub>2</sub>

White:(+)ve values ; Convex  
 Black:(-)ve values ; Concave  
 Grey: near 0 ; Valley

# Binary Decision Tree

A decision support tool that uses a tree-like model of decisions and their possible consequences



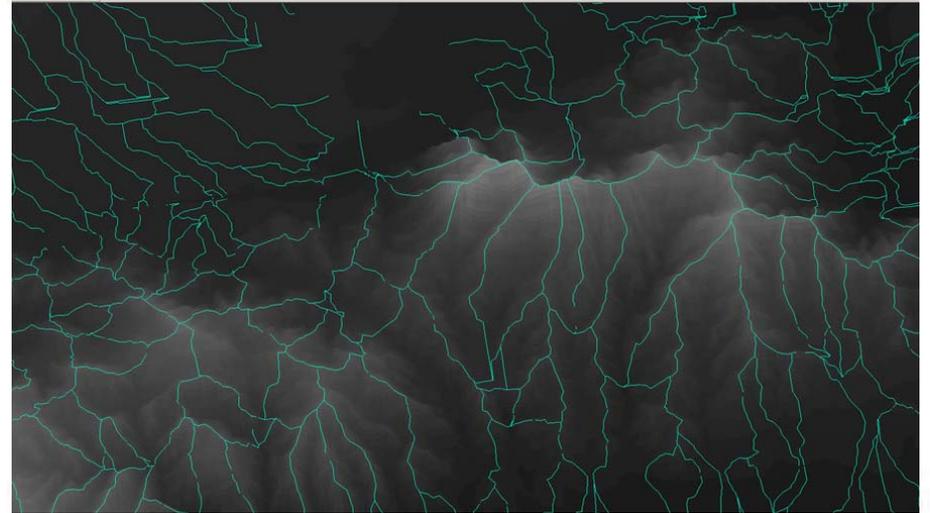
Where, sT1 is Standardized TPI<sub>500</sub>, sT2 is Standardized TPI<sub>300</sub>, Cur is Curvature, μ is mean curvature & σ is standard deviation value of curvature.



# Results



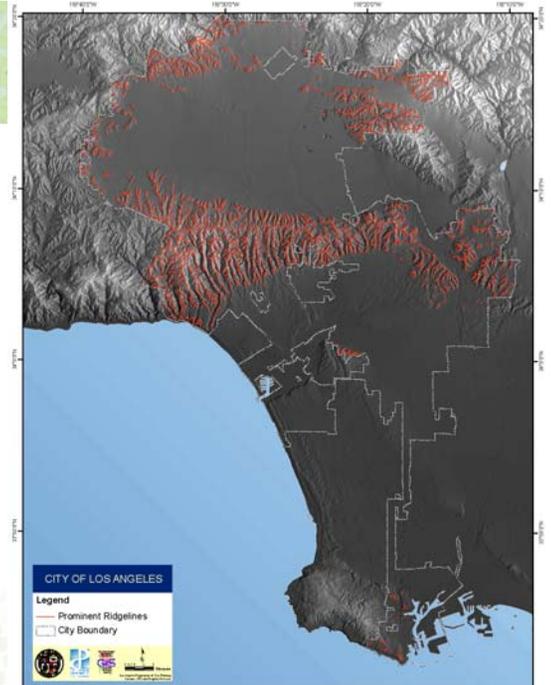
## Hollywood Area – Watershed boundaries



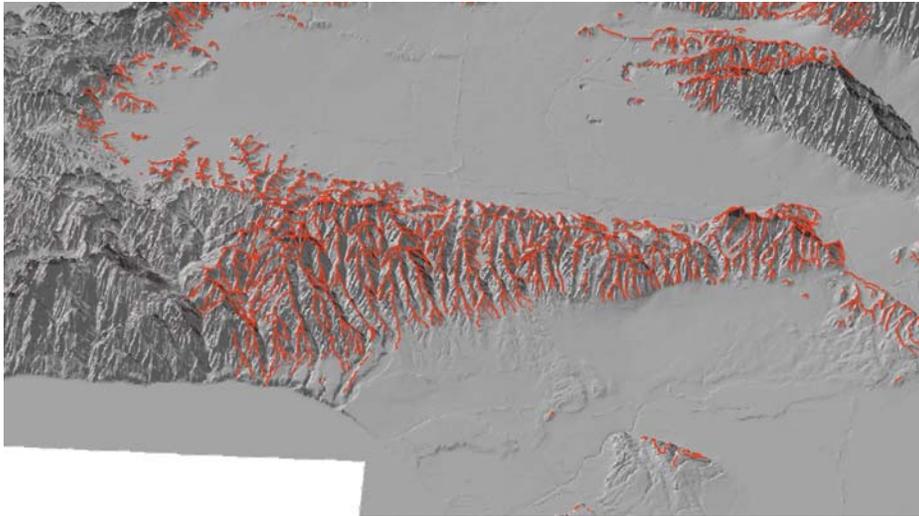
## Hollywood Area – Ridgelines After applying Decision Tree Algorithm



## City-wide Ridgeline Map



## 3D Model

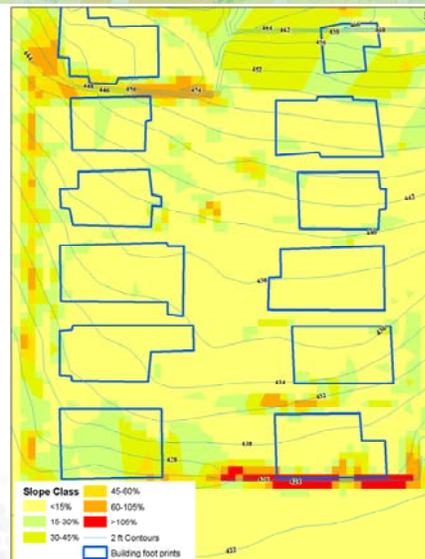


## Conclusions

- **Watershed Delineation process can be used to identify the location of ridgelines.**
- **Decision tree successfully discriminates ridgeline points from other valley and depression points.**
- **GIS based 3D Visualization provides sufficient realism for accuracy assessment.**
- **Automated ridgeline extraction process helps to save significant amount of staff time.**

## Challenges in using LAR-IAC 2 ft DEM data

- **Capacity of Data set for citywide study.**
- **Elevation differences created at edges of roofs.**
- **Vast elevation difference in building foot prints .**



## Challenges in using LAR-IAC 2 ft DEM data



If height model has a mixture of points on top of the vegetation or buildings and points on the ground, the points not located on the ground should be able to removed by filtering.

e.g.: Hannover Program RASCOR  
(Passini et.al., 2002)

A decorative header image featuring a map of a city grid with green spaces and roads.

## Acknowledgement

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